

# NETWORK CODING OVERHEAD

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# Introduction & Motivation

- Network coding **optimizes** multicast rates to max-flow min-cut bound (Ahlsvede, et. al. '00).
- Plain routing is **not** optimal & **Linear** network coding is **sufficient** (Li, et al. '03, Koetter-Medard '03).
- **Typical assumption:** Destinations know how packets are network-coded.

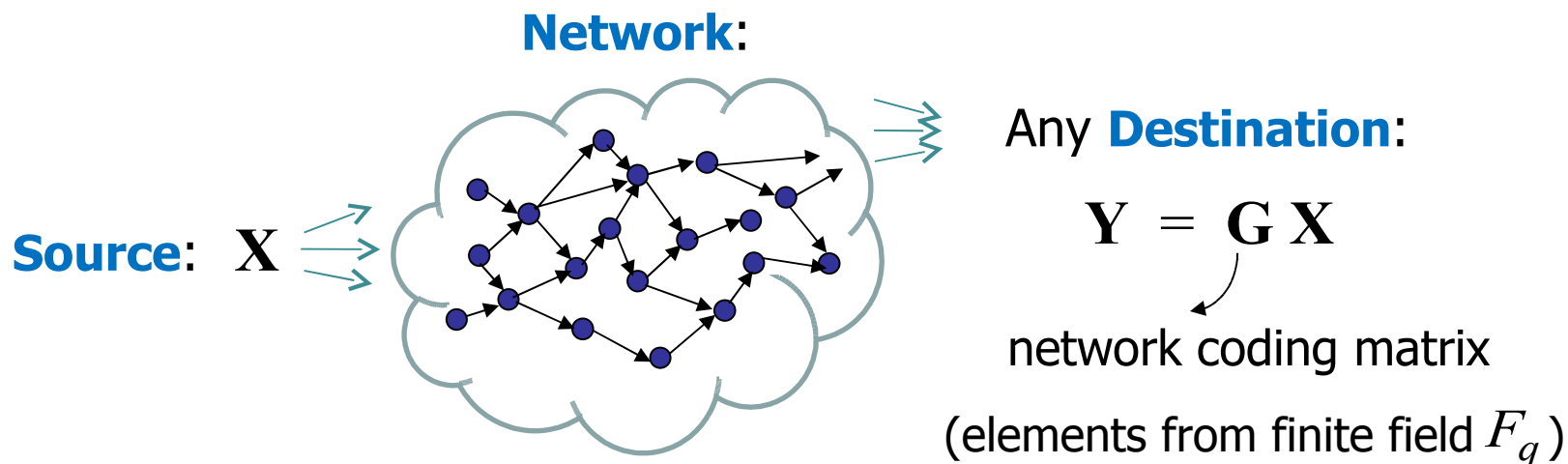
## Protocol Information

Header ?

Data Symbols

- Limiting effects of network coding **overhead**.
- Joint channel **coding/training** for robust network coding.

# Network Coding Overhead

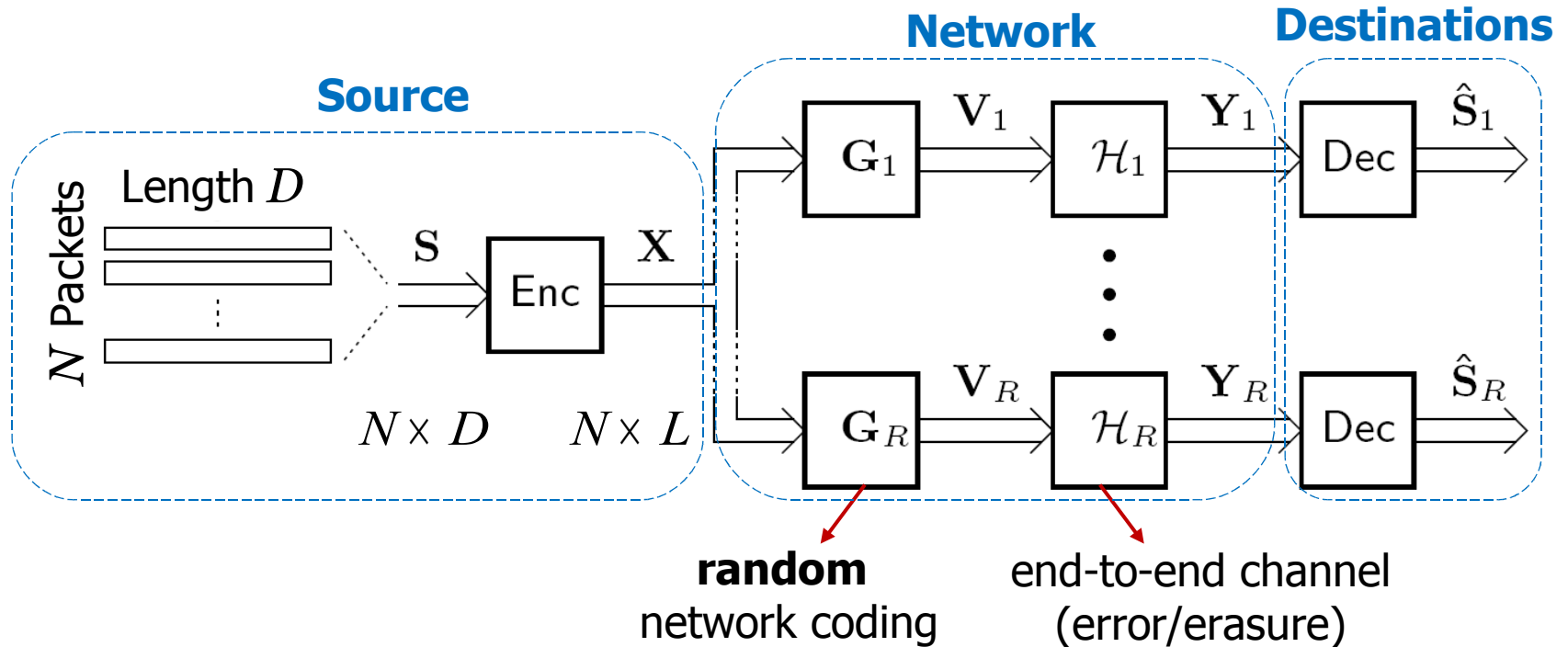


- Distributed solution: **Random network coding** (Ho, et. al '06) .
- Communicate “ $\mathbf{G}$ ” to destinations in packet header: 

$\mathbf{G}$	Data
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- **Challenge:** Decoding **impossible**, if error/erasure in “ $\mathbf{G}$ ” .

# System Model for Overhead Analysis

- **Question:** What is **overhead** for reliable communication of “G” & data?



- **Unknown** topology & “G” (*i.i.d* assumption).

# Network Coding Meets MIMO: Training Approach

- Detection of network coding matrix  $\mathbf{G} \Leftrightarrow$  **MIMO** channel estimation.
- Source transmits **known training** sequence  $\mathbf{X}_T$ .

- Destination  $d$  receives  $\mathbf{Y}_d = \mathcal{H}_d(\underbrace{\mathbf{G}_d}_{\text{Rows of } \mathbf{G}_d \text{ are encoded by } \mathbf{X}_T} \mathbf{X}_T)$ .

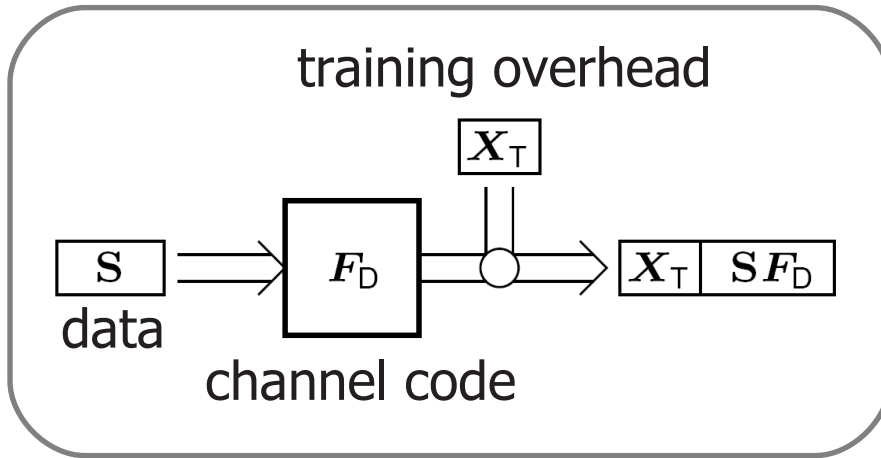
Rows of  $\mathbf{G}_d$  are encoded by  $\mathbf{X}_T$

- **Interpretation:**  $\mathbf{X}_T$  is a “code” generator matrix (e.g., MDS code)

Rows of  $\mathbf{G}_d$  are the transmitted “packets”

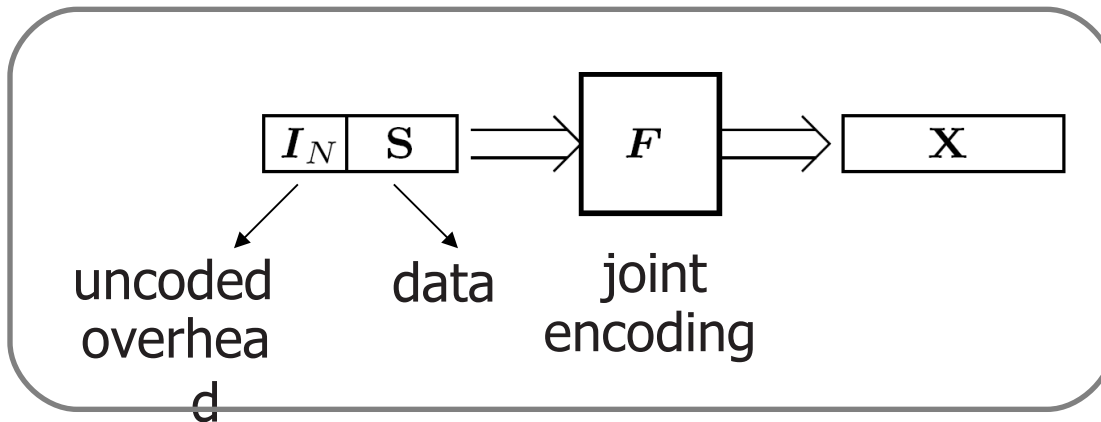
# Encoding with Training

- **Separate training and coding** (STC).



$$\mathbf{X} = [\mathbf{X}_T \ \mathbf{S}F_D] = [\mathbf{I}_N \ \mathbf{S}] \begin{bmatrix} \mathbf{X}_T & \mathbf{0} \\ \mathbf{0} & F_D \end{bmatrix}$$

- **Joint training and coding** (JTC).



$$\mathbf{X} = [\mathbf{I}_N \ \mathbf{S}]F$$

# Decoding Channel & Network Codes

(1) Decode **channel code**:  $\left\{ \begin{array}{l} \hat{G}_d \text{ for random network coding matrix } G_d \\ \hat{U}_d \text{ for network-coded data: } U_d = G_d S \end{array} \right.$   
(S: source packets)

**JTC: Jointly** decode entire packet.  $\left. \begin{array}{l} \text{JTC: Jointly} \\ \text{STC: Separately} \end{array} \right\}$  Maximum Likelihood (ML) estimates  
**STC: Separately** decode training and data parts.

(2) Decode **network code**:

– Solve  $\hat{U}_d = \hat{G}_d \hat{S}_d$  for data  $\hat{S}_d$  from ML estimates  $\hat{G}_d$  and  $\hat{U}_d$ .

# Throughput & Overhead

- Two types of decoding **error**:
  - Errors/erasures in packets
  - Rank-deficient network coding matrix  $\hat{G}_d$
- **Decoding probability**  $P_d$  is derived via **random coding bounds**.

- End-to-end achievable **rate**:

$$\Lambda^* = \max_{N,D} \left[ N \frac{D}{L} \min_d P_d \right]$$

- **Overhead:**  $O = \frac{L - D}{L}$

$N$ : independent messages per transmission

$D$ : data symbols per packet

$L$ : total packet length

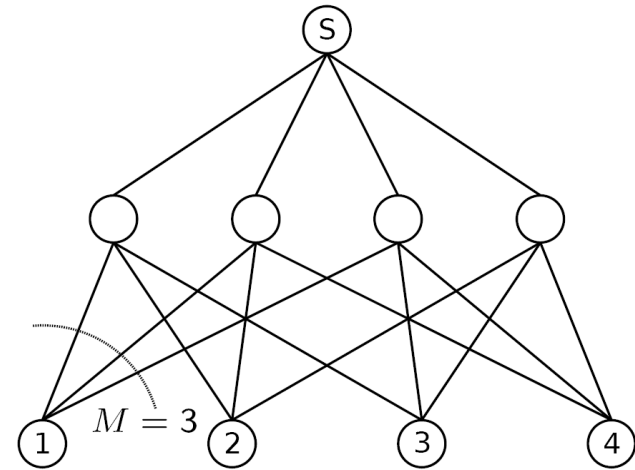
# Limiting Effects of Overhead

## Example 1: Combination network

1 source

$A$  layer-2 nodes

$\binom{A}{M}$  destinations

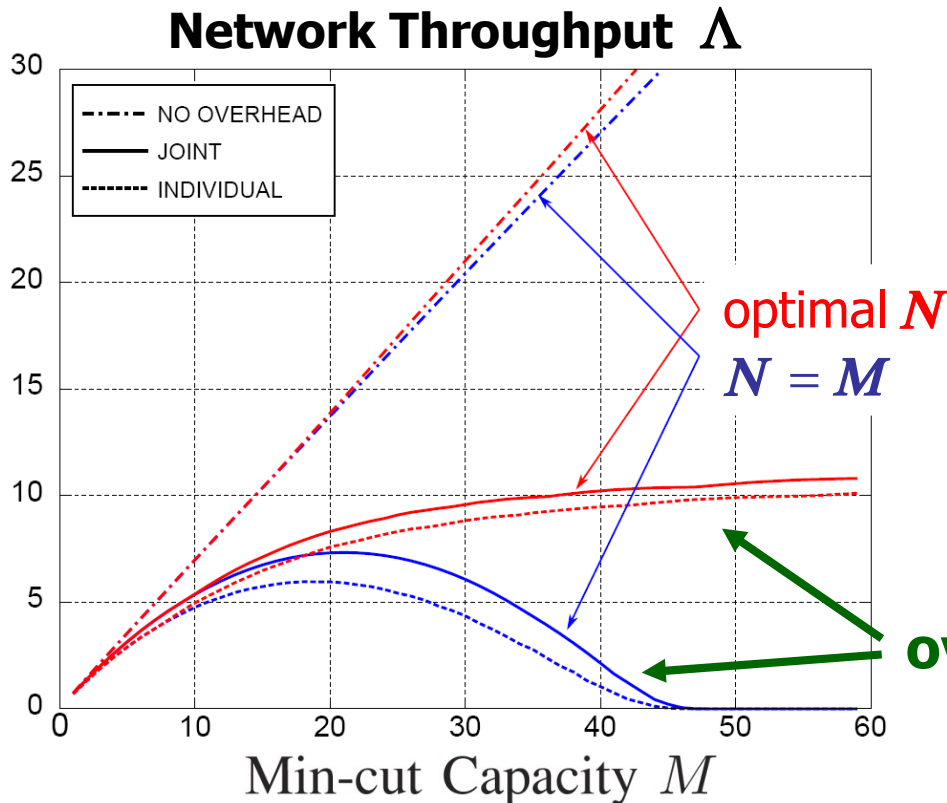


$M$ : min-cut capacity

Field  $q = 2^8$ , 480 bits per packet,

$\binom{60}{M}$  combination network,

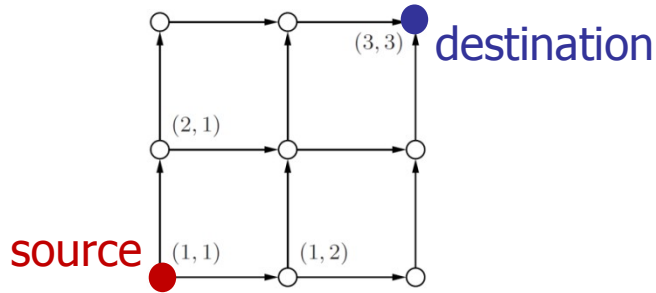
bit erasure probability  $10^{-2}$



overhead kicks in

# Throughput-Overhead Performance (Cont'd)

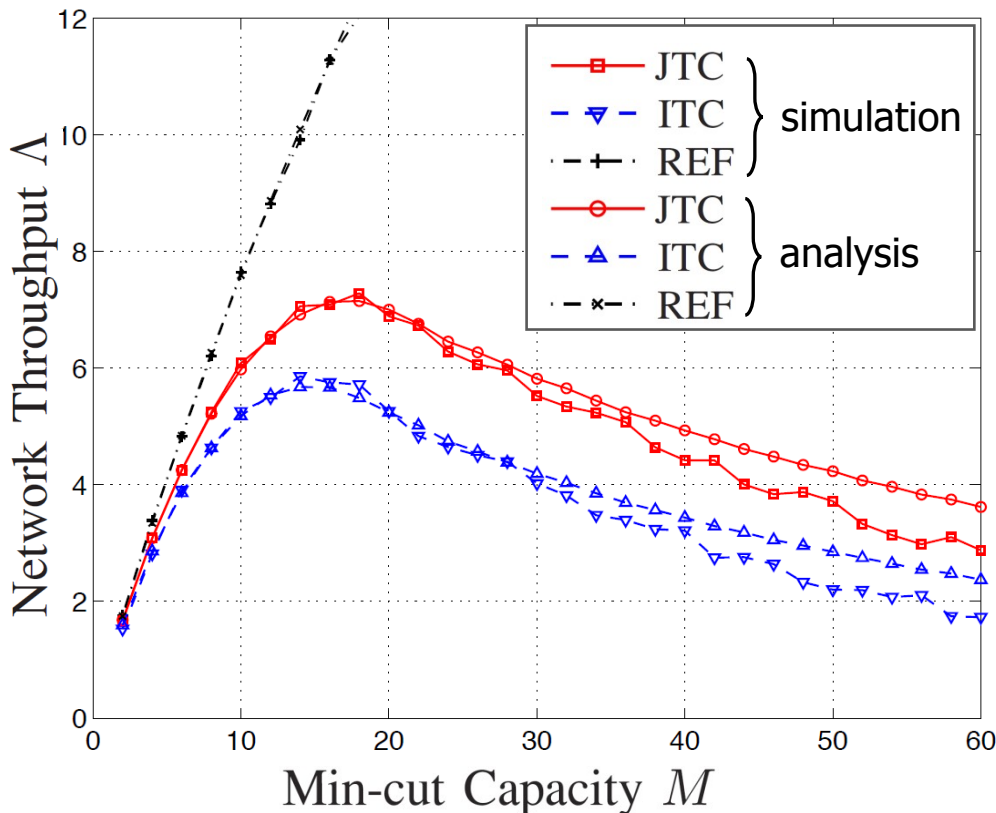
## Example 2: Grid network



Each link carries  $M/2$  packets per time slot

Field  $q = 2^8$ , 60 bits per packet

Bit error probability  $10^{-3}$



**JTC:** Joint training & coding

**ITC:** Individual training & coding

**REF:** Destination knows "G"

**analysis:** Random coding bound on probability of successful decoding

**simulation:** Average error rates over random coding matrices & error events with MDS channel codes

# End-to-End Distributed Network Coding

- Oblivious to network topology (mobility effects, malicious behavior, ...).
- **No** need to know network coding matrix "G".
- Need to know min-cut capacity  $M$  (s.t.  $N \leq M$ )  $N$  : independent messages per transmission
- **Rate control:** Adapt  $N$  based on destination feedback (ACK/NACK).
  - Increase  $N$ , if channel & network codes are successfully decoded.
  - Decrease  $N$ , otherwise.

# Conclusions

- **Training** can be combined with **channel coding**.
  - Enables **joint** decoding of data and network coding matrix.
  - Simplifies and balances protection of **overhead**.
- Network coding gain is **limited** by the necessary protocol overhead.
  - Overhead **grows** with the min-cut capacity.
- **Future Work:**
  - Extension to **general** error and erasure models.
  - Exploit **redundancy** in sequence of coding matrices.
  - **Adaptive** training and feedback schemes to learn error statistics.