

Path Loss Exponent Estimation in Large Wireless Networks

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Motivation

- Large-scale path loss law: signal strength attenuates with distance d as d^γ

$$S \propto \left(\frac{d}{d_0} \right)^{-\gamma} .$$


- Though it is typically assumed in analysis and design problems that the path loss exponent (PLE) is known a priori, it is often not the case.
- The PLE has a strong impact on the quality of links, and therefore needs to be accurately estimated for the efficient design and operation of systems.

Motivation (contd.)

- **Example 1:** The information-theoretic capacity of large random ad hoc networks scales as *

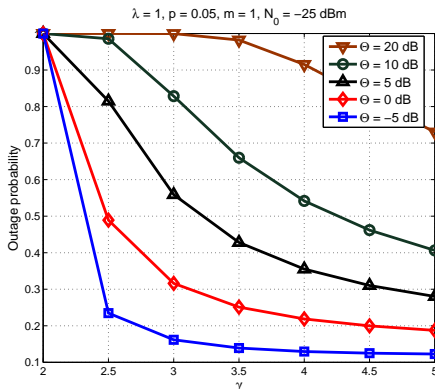
$$\begin{aligned} n^{2-\gamma/2} & \text{ for } 2 \leq \gamma < 3 \\ \sqrt{n} & \text{ for } \gamma \geq 3. \end{aligned}$$

Depending on the value of γ , different routing strategies are required to be implemented.

*A. Özgür, O. Lévêque and D. Tse, "Hierarchical Cooperation Achieves Optimal Capacity Scaling in Ad Hoc Networks," *IEEE Trans. Info. Th.*, 2007. 

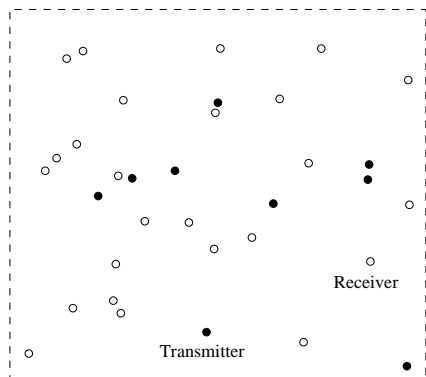
Motivation (contd.)

- **Example 2:** Outage probability in a planar Poisson point process with Rayleigh fading.



The system performance critically depends on γ .

System Model



Filled circles: transmitters.
Empty circles: receivers.

- An infinite Poisson point process (PPP) on \mathbb{R}^2 with density λ .
- Channel access scheme is ALOHA.
- p is the ALOHA contention parameter. Therefore, the set of transmitters forms a PPP with density λp .
- No synchronization.

System Model (contd.)

- Attenuation in the channel: product of
 - large-scale path loss, with PLE γ .
 - small-scale fading (m -Nakagami).
 $m = 1$: Rayleigh fading ; $m \rightarrow \infty$: no fading.
- Noise is AWGN with variance N_0 .
- All the transmit powers are equal to unity (no power control).

Problem: How do you accurately estimate the PLE at each node in the network in a completely distributed manner?

What Makes Estimating the PLE Complicated?

- The large-scale path loss is commonly taken to be **deterministic** while the small-scale fading is modeled as a **stochastic** process.
- This distinction, however, does not hold when the nodes themselves are randomly arranged. So, we **need to consider the distance and fading ambiguities jointly**.
- Moreover, PLE estimation needs to be performed during the initialization of the network. During this phase, **the system is typically interference-limited** due to the presence of uncoordinated transmissions.

Purely RSS-based estimators cannot be used in these situations.

- Propose three distributed algorithms for estimating the PLE in large random wireless networks that explicitly take into account
 - the uncertainty in the locations of the nodes.
 - the uncertainty in the fading gains across links.
 - the interference in the network.
- Provide simulation results to demonstrate the performance of the algorithms and quantify the estimation errors.

The Big Picture

- The PLE estimation problem is essentially tackled by **equating the empirical (observed) values** of certain network characteristics **to their theoretically established values**.
- By obtaining measurements over several time slots, the PLE can be estimated at each node in a distributed fashion.
- The three PLE algorithms are **each based on a specific network characteristic**:
 - the mean interference.
 - the outage probability.
 - connectivity properties of a node.

Simulation Details

- We use 50,000 different realizations of the PPP to analyze the mean error performance of the algorithms, which is characterized using the 'relative' MSE, defined as $\mathbb{E} \left[(\hat{\gamma} - \gamma)^2 \right] / \gamma$.
- We used $p = 0.05$ since it was suitable. Note the tradeoffs.
 - **Large** p : results in few quasi-different realizations of the transmitter PPP.
 - **Small** p : takes long for the algorithms to convergence.

Algo. 1: Using the Mean Interference


- This algorithm assumes that the network density λ is known.
- In theory, the mean interference is given by [†]

$$\mu = 2\pi\lambda p A_0^{2-\gamma} / (\gamma - 2), \quad (1)$$

where A_0 is the near-field radius of the antenna.

Implementation

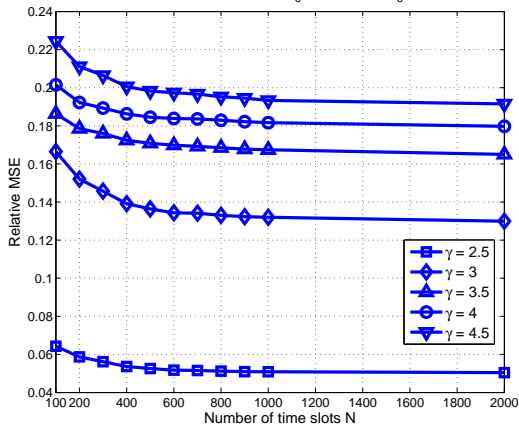
- Nodes simply need to record the mean strength of the received power, μ' , averaged over several time slots.
- Equating μ to μ' , and using the known values of p , A_0 , and λ , $\hat{\gamma}$ is found from a look-up table.

[†]J. Venkataraman, M. Haenggi and O. Collins, "Shot Noise Models for Outage and Throughput Analyses in Wireless Ad Hoc Networks," *MILCOM*, 2006. 

Algo. 1: Using the Mean Interference (contd.)

Relative MSE of $\hat{\gamma}$ versus the number of time slots.

$$\lambda = 1, \rho = 0.05, m = 1, N_0 = -25 \text{ dBm}, A_0 = 1$$



The estimates are fairly accurate over a wide range of parameters.

Algo 2: Based on (Virtual) Outage Probabilities

- This algorithm does not require the knowledge of λ or m .
- In a PPP, when the signal power is exponentially distributed, the probability of a successful transmission p_s is

$$p_s = \mathbb{P}(\text{SIR} > \Theta) = \exp(-c\Theta^{2/\gamma}), \quad (2)$$

where $c = \lambda p \pi \Gamma\left(m + \frac{2}{\gamma}\right) \Gamma\left(1 - \frac{2}{\gamma}\right) / (\Gamma(m) m^{2/\gamma})$.

- Nodes can determine the SIR, and consequently p_s by computing the ratio of the power of the signal (which arrives from a virtual transmitter, and is assumed to be exponentially distributed) and the total received power.

Algo 2: Based on (Virtual) Outage Prob. (contd.)

Implementation: A 'differential' method.

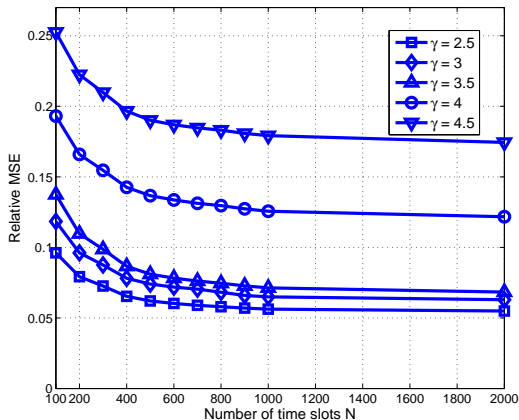
- Obtain a histogram of the observed SIR values measured over several time slots.
- The empirical success probabilities ($p_{s,i} = \mathbb{P}(\text{SIR} > \Theta_i)$, $i = 1, 2$) are obtained at two different threshold values.
- Inverting (2), an estimate of γ is obtained as

$$\hat{\gamma} = \frac{2 \ln(\Theta_1/\Theta_2)}{\ln(\ln p_{s,1}/\ln p_{s,2})}. \quad (3)$$

Algo 2: Based on (Virtual) Outage Prob. (contd.)

Relative MSE of $\hat{\gamma}$ versus the number of time slots.

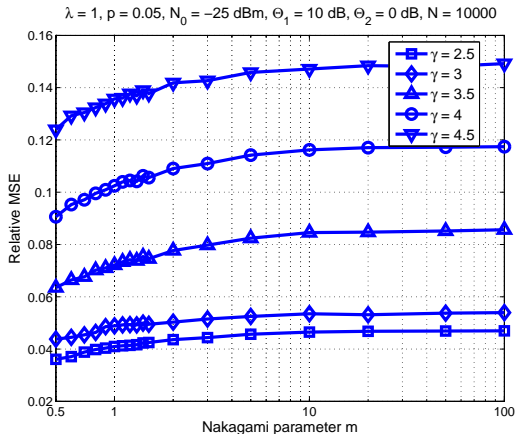
$\lambda = 1, p = 0.05, m = 1, N_0 = -25$ dBm, $\Theta_1 = 10$ dB, $\Theta_2 = 0$ dB



The estimation error increases with larger γ .

Algo 2: Based on (Virtual) Outage Prob. (contd.)

Relative MSE of $\hat{\gamma}$ versus the Nakagami parameter.



This algorithm performs more accurately at lower values of m .

Algo 3: Based on the Cardinality of the T_x Set

- This algorithm also does not require to know m or λ .
- Transmitter node y is in receiver node x 's *transmitting set*, $T(x)$ if they are connected, i.e., the SIR at x due to y 's signal is $> \Theta$.
- We prove that under the conditions of $m \in \mathbb{N}$,

$$\mathbb{E}|T(x)| = \bar{N}_T = \frac{\Gamma(m) \left(1 - \left(\frac{2}{\gamma}\right)^m\right)}{\Gamma\left(m + \frac{2}{\gamma}\right) \Gamma\left(2 - \frac{2}{\gamma}\right) \Theta^{2/\gamma}}. \quad (4)$$

- We see that \bar{N}_T is inversely proportional to $\Theta^{2/\gamma}$, and surmise that this behavior holds at arbitrary $m \in \mathbb{R}^+$.

Algo 3: Based on the Card. of the Tx Set (contd.)

Implementation

- For a known threshold $\Theta_1 \geq 1$, at time slot i , $1 \leq i \leq N$, set

$$N_{T,1}(i) = \begin{cases} 1 & \text{if the node can decode a packet} \\ 0 & \text{otherwise.} \end{cases}$$

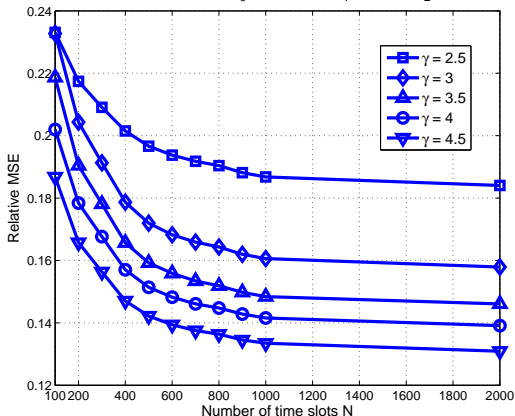
- Evaluate $\bar{N}_{T,1}$ and $\bar{N}_{T,2}$ at two different threshold values Θ_1 and Θ_2 respectively.
- In theory, we obtain $\bar{N}_{T,1}/\bar{N}_{T,2} = (\Theta_2/\Theta_1)^{2/\gamma}$.
- Inverting this, we have

$$\hat{\gamma} = (2 \ln(\Theta_2/\Theta_1)) / \ln(\bar{N}_{T,1}/\bar{N}_{T,2}). \quad (5)$$

Algo 3: Based on the Card. of the Tx Set (contd.)

Relative MSE of $\hat{\gamma}$ versus the number of time slots.

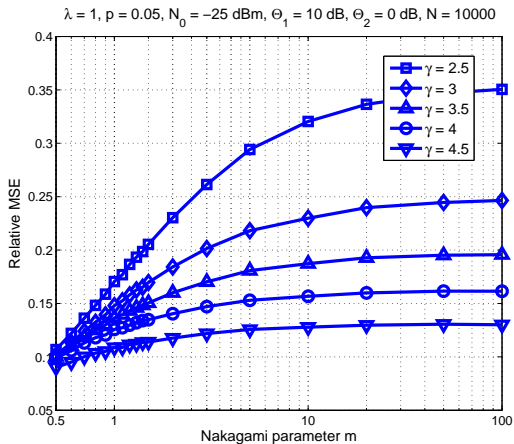
$\lambda = 1$, $p = 0.05$, $m = 1$, $N_0 = -25$ dBm, $\Theta_1 = 10$ dB, $\Theta_2 = 0$ dB



In contrast to Algo. 1 and 2, the relative MSE decreases with γ .

Algo 3: Based on the Card. of the Tx Set (contd.)

Relative MSE of $\hat{\gamma}$ versus the Nakagami parameter.



The estimates are more accurate at lower m.

Summary and Discussion

- We have addressed the PLE estimation problem in the presence of node location uncertainties, m -Nakagami fading and most importantly, interference!
- Each of the algorithms are fully distributed and do not require any information on the location of other nodes or the value of m .
- Based on the relative MSE values, we conclude that at low values of γ , Algo. 1 performs the best (though it requires the density to be known), while when γ is high, Algo. 3 is preferred.

Summary and Discussion (contd.)

- Each of our algorithms work by equating empirical values with their corresponding theoretically established ones.
- The caveat is that the theoretical results are for an “average network” while in practice, we have only a single realization of the node distribution at hand. Thus, in general, the estimates we obtain are biased.
- This also explains the fact that the performance of Algorithms 2 and 3 is better at lower m .
- We remark that the bias (and the MSE) can be significantly lowered if nodes have access to several independent realizations of the point process or if they are allowed to communicate.