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*Communications  
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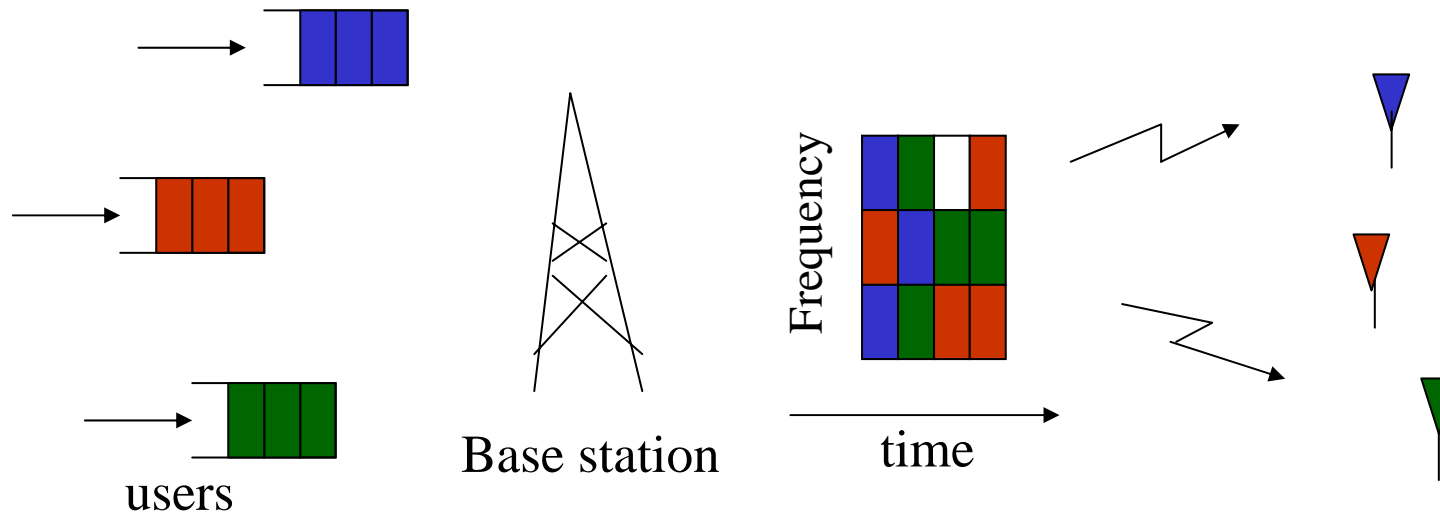


# An Adaptive Limited Feedback Scheme for MIMO-OFDMA Based on Optimal Stopping

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## Downlink OFDMA



- Allocate frequency slots among users at each scheduling interval.
- **Objective:** maximize sum rate
  - Exploit channel state information (CSI) at Base Station (BST).



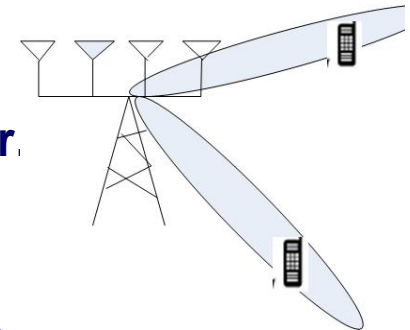
## Downlink Feedback Problem

- Overhead for acquiring complete channel info. is prohibitive.
  - Full CSI at transmitter (BST) scales with number of users  $K$  and number of sub-channels  $N$ .
- How can we reduce the feedback overhead while retaining performance benefits?
  - Must balance uplink overhead with downlink performance.



## System Model For MIMO-OFDMA

- Downlink model:  $K$  receivers,  $N$  OFDM sub-channels.
- $M$  antenna at the base station. Single antenna at the receiver.
  - Can support up to  $M$  data streams.
- Every user uses the **same** codebook with size  $M$ .
- Every user calculates the **worst case SINR** on each beam/sub-channel
  - assuming  $M$  data streams will be transmitted at the same time.
- Complete CSI requires feeding back  $K \cdot N \cdot \log M$  channel coefficients per coherence time...





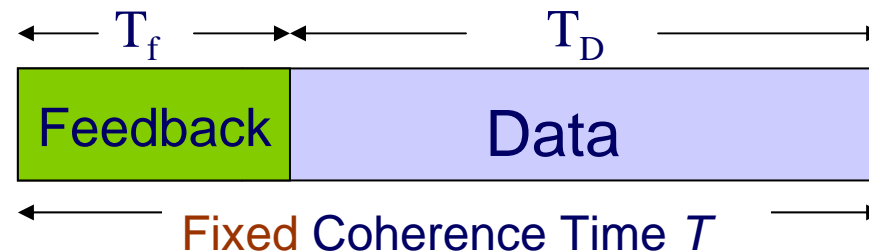
## Feedback Model with Fixed Coherence Time



- Time division duplex (TDD) model
  - 1 frame = 1 coherence time  $T$ .
- First part of frame used for feedback from users. Second part of frame for data transmissions to scheduled users.
- Fixed feedback rate  $R_F$  per sub-channel.
  - Total feedback bits per coherence time  $\leq N R_F T$
- Objective: maximize the sum capacity taking the time for feedback into consideration.



## Feedback and Data Tradeoff



- Larger  $T_f$  benefits the resource allocation at the base station
  - Better exploit multiuser diversity and frequency diversity
- Smaller  $T_f$  implies more time for data transmission (larger  $T_D$ )
- Previously studied **fixed**  $T_f$  schemes for OFDMA [JSAC08]
- Here: **adaptive**  $T_f$  scheme for MIMO-OFDMA
  - based on feedback received within the coherence time  $T$ .
  - Optimal stopping problem.



# Beam Selection

- Beams are selected from a codebook

$$\mathcal{V} = \{\mathbf{v}_1, \dots, \mathbf{v}_M\}$$

- For each sub-channel  $i$ , user  $k$  computes [Yoo, et. al JSAC07]:

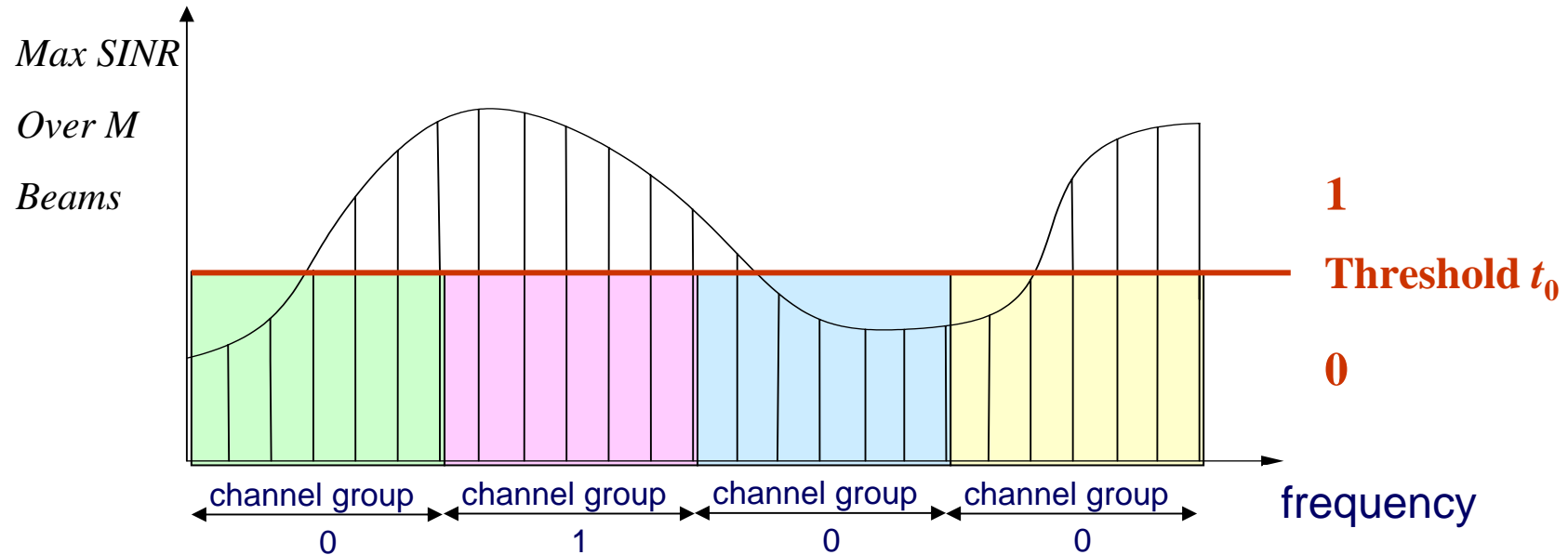
- $m_{k,i} = \arg \max_n \{|\mathbf{v}_n^\dagger \mathbf{h}_k|\}$  (receiver knows  $\mathbf{h}_k$ )

- The SINR for beam  $m_{k,i}$  assuming all other  $M-1$  beams are also active (worst-case).

- User  $k$  requests beam  $m_{k,i}$  if the associated worst-case SINR exceeds the threshold  $t_0$ .



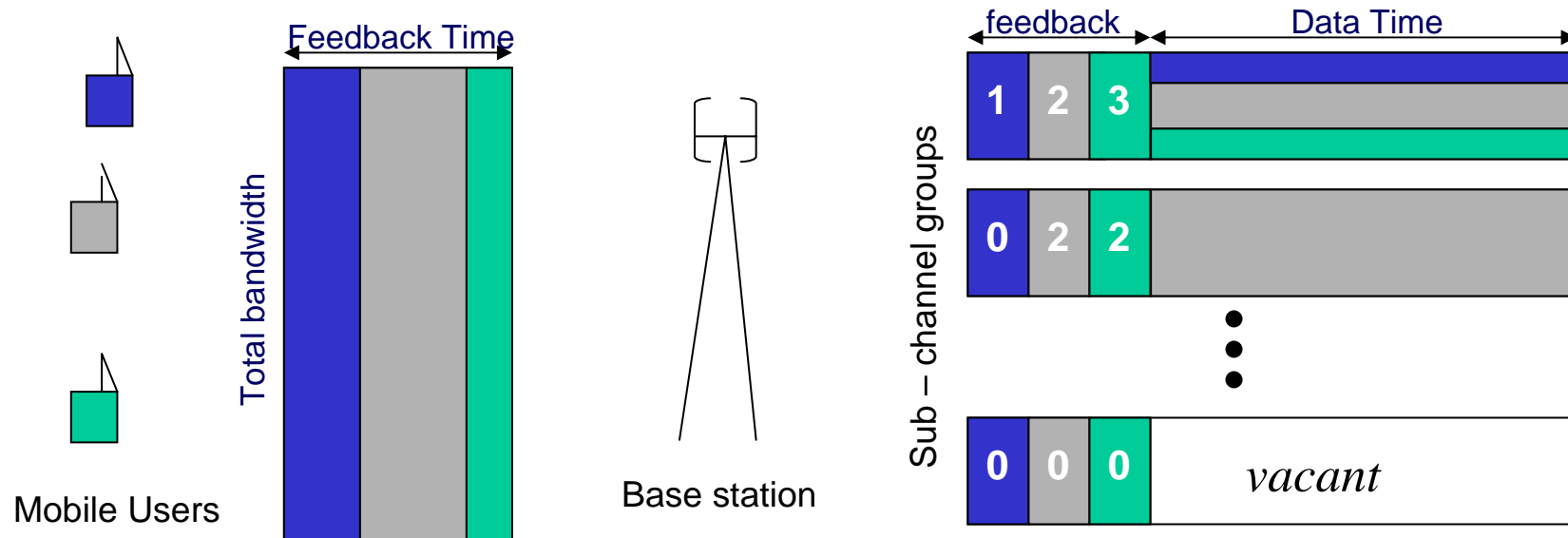
# Sub-Channel Groups



- Each sub-channel group contains  $\alpha N$  sub-channels,  $0 \leq \alpha \leq 1$ .
- A user requests a sub-channel group if **all worst-case SINRs** in that group  $> t_0$ .



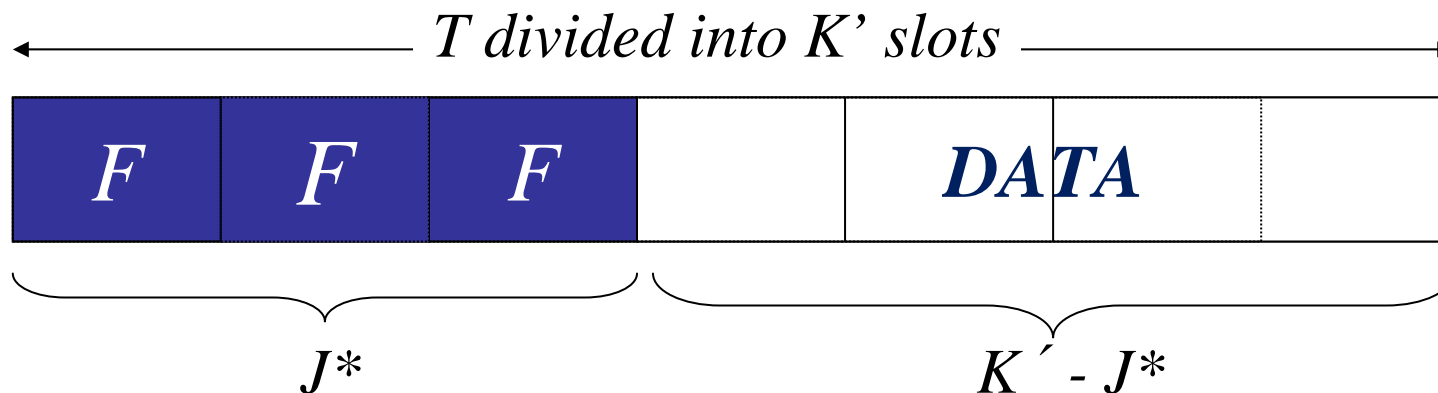
# Feedback Scheme



- Users feedback **compressed** requests **sequentially**.
- If a beam for a sub-channel is requested by **>1** user, the base station **randomly** assigns one of them to that sub-channel.



# Adaptive Feedback



- Coherence time  $T$  divided into  $K'$  slots.
  - At most 1 user can feedback compressed requests/slot.
- Feedback *adaptively* stops after  $J^*$  slots.



# Optimal Stopping Rule

- One-step look-ahead policy (given  $K'$ ):

Stop at slot  $n$  if  $R_n \geq E(R_{n+1} | s_n)$

$R_n$  is the rate after  $n$  feedback slots:

$$\left(1 - \frac{n}{K'}\right) \sum_{i=1}^M (ix_{i,n}) \log(1 + t_0)$$

$x_{i,n}$  = number of sub-channels on which  $i$  data streams have been requested at time  $n$ .

$$s_n = [x_{0,n}, \dots, x_{M,n}]$$

- From this  $J^*$  can be obtained in closed-form.



## Results Outline

- Given fixed  $R_F T$ , the system size  $K$  and  $N$  scale with fixed ratio  $K/N$ .
  - Each user feedback slot converges to same length by law of large number
- The sum capacity is optimized over system parameters
  - Number of slots  $K'$
  - Sub-channel group size
  - Threshold
  - Requesting probability of a sub-channel group



# Scaling Properties

- Given fixed  $R_F T$ , the sum capacity scales linearly with  $N$ .
  - Holds for **any** load  $K/N$ .
  - Not true for previous (non-adaptive) policies.
- Optimal system parameters:
  - Number of slots  $K'$  scales as  $K' \log K' = O(K)$
  - Sub-channel group size scales as  $O(\log K')$
  - Each user requests a finite number of sub-channel groups on average.
  - Average stopping time  $J^*$  scales as  $O(K')$

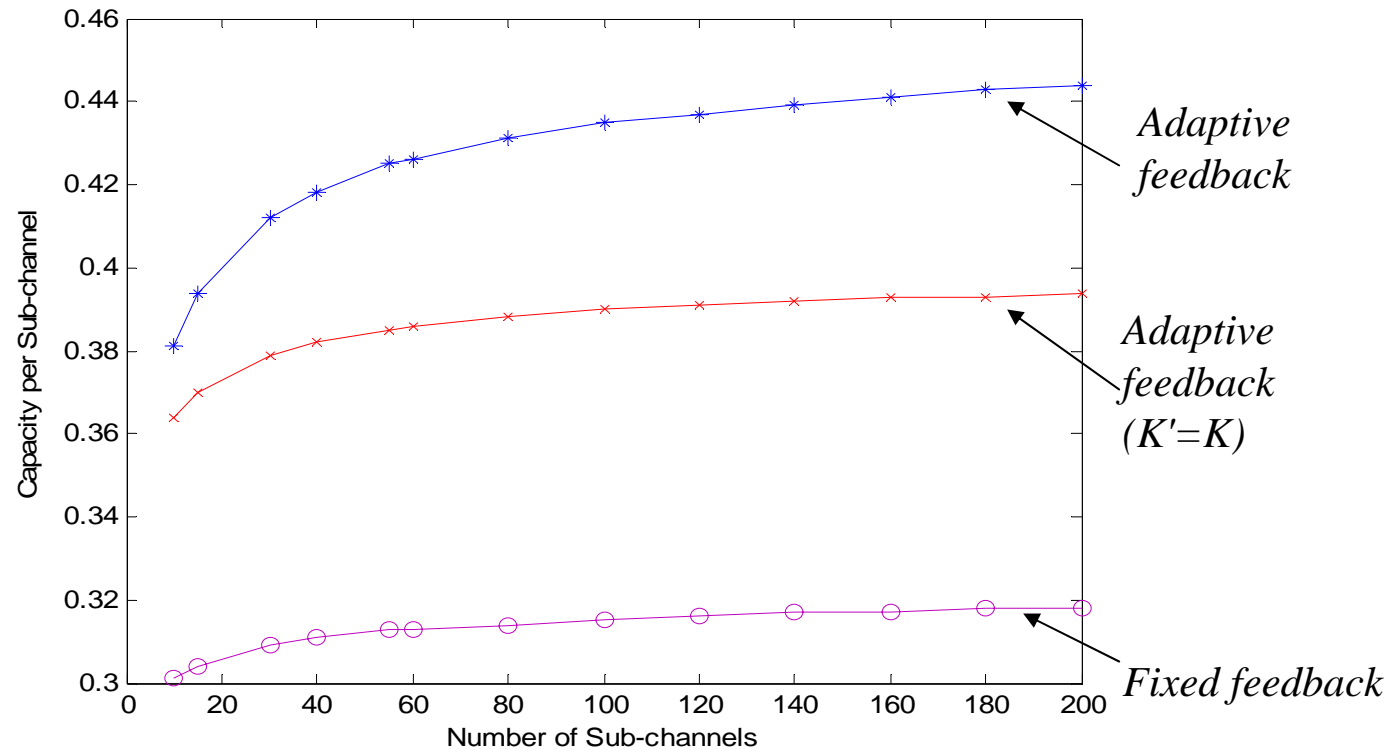


# Capacity vs Feedback

- If  $R_F T$  increases slower than  $\log K$ , then the achievable rate per sub-channel increases as  $M \log (R_F T / (M-1))$ .
- If  $R_F T$  increases faster than  $\log K$ , then the achievable rate per sub-channel increases as  $M \log \log K$ .



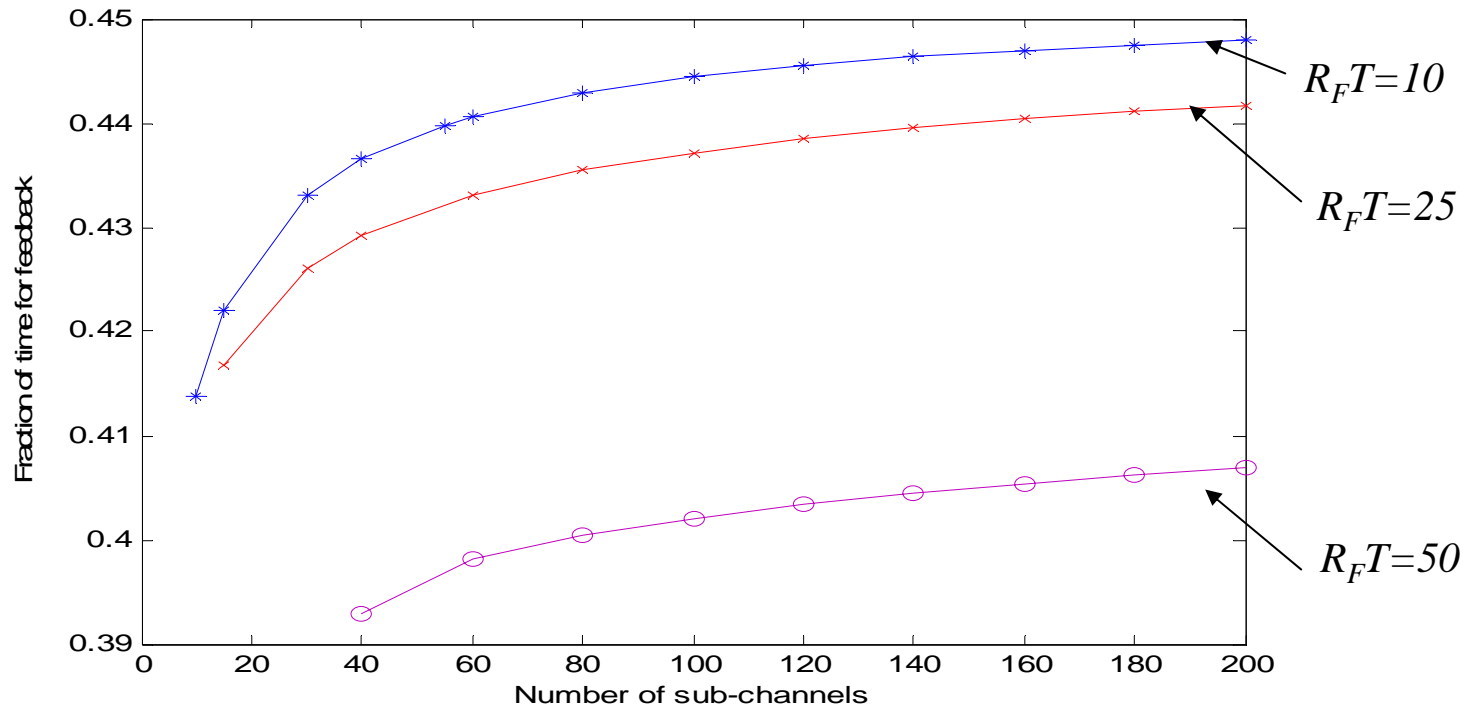
# Performance Comparison



$$R_F T = 10, P = 1.5, M = 4, K/N = 2$$



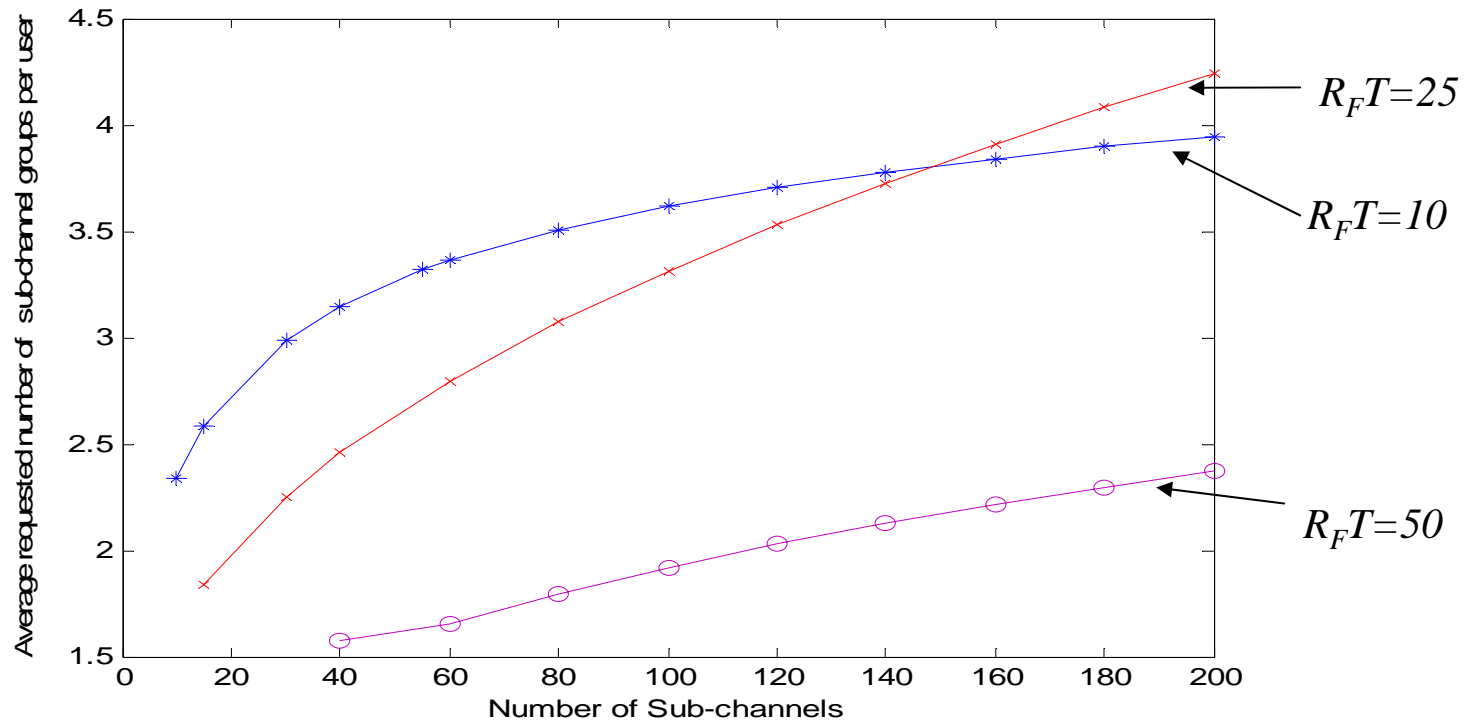
# Fraction of Time for Feedback



$$P=1.5, M=4, K/N=2$$



# Requested Sub-Channel Groups/User



$$P=1.5, M=4, K/N=2$$



## Conclusions

- Presented a scalable limited-feedback scheme for downlink MIMO-OFDMA.
  - Explicitly accounts for feedback overhead.
  - Optimal stopping provides scalability with users; improves on static feedback for all parameter ranges.
- Several assumptions can be revised in future work:
  - Larger codebook size
  - Temporally correlated channels
  - Overhead due to downlink signaling